

Spectral analysis of terrestrial planets and gas giants

Gas giants have a discrete (acoustic) spectrum, part III

M.V. de Hoop

J. Ilmavirta, A. Kykkänen, R. Mazzeo

Rice University

Simons Foundation MATH + X, NSF-DMS, DOE BES
Geo-Mathematical Imaging Group, Oxy

University of Ghent

Oscillation phenomena, PDEs and applications
October 2025

Recall from the first lecture

The acousto-gravitational system of equations (equation (11) in the first lecture)

$$\partial_t^2(\rho_0 u) + 2\Omega \times \partial_t(\rho_0 u) = \nabla[c^2(\nabla \cdot (\rho_0 u) - \tilde{s} \cdot u)] - (\nabla \cdot (\rho_0 u))g'_0 - \rho_0 \nabla S(\rho_0 u). \quad (1)$$

The equation comes together with the free-surface boundary condition

$$[\nabla \cdot u]|_{\partial M} = 0.$$

So far we have assumed the planet to be artificially truncated so that $c^2 > 0$.

In this lecture we let the sound speed c go zero at ∂M . We will see that to the **leading order** the equation becomes a wave equation for a Riemannian metric which is singular at ∂M .

Recall from the first lecture

The acousto-gravitational system of equations (equation (11) in the first lecture)

$$\partial_t^2(\rho_0 u) + 2\Omega \times \partial_t(\rho_0 u) = \nabla[c^2(\nabla \cdot (\rho_0 u) - \tilde{s} \cdot u)] - (\nabla \cdot (\rho_0 u))g'_0 - \rho_0 \nabla S(\rho_0 u). \quad (1)$$

The equation comes together with the free-surface boundary condition

$$[\nabla \cdot u]|_{\partial M} = 0.$$

So far we have assumed the planet to be artificially truncated so that $c^2 > 0$.

In this lecture we let the sound speed c go zero at ∂M . We will see that to the [leading order](#) the equation becomes a wave equation for a Riemannian metric which is singular at ∂M .

Extracting the Laplacian

- neglecting the Coriolis term and the lower-order terms the acousto-gravitational system becomes

$$\partial_t^2(\rho_0 u) = \nabla[c^2(\nabla \cdot (\rho_0 u) - \tilde{s} \cdot u)] = \nabla[c^2 T u]$$

- we use the generalized Helmholtz decomposition (Lemma 2 in the first lecture) to write $u = T^*(\rho_0 \varphi) + u_2$ with $\varphi \in H^1(M)$ and $u_2 \in \text{Ker}(T)$; the equation becomes

$$\partial_t^2(T^*(\rho_0 \varphi)) + \partial_t^2 u_2 = \rho_0^{-1} \nabla[c^2 T T^*(\rho_0 \varphi)].$$

- setting $u_2 = 0$ and replacing ∇ with T^* to obtain

$$\partial_t^2(T^*(\rho_0 \varphi)) = \rho_0^{-1} T^*[c^2 T T^*(\rho_0 \varphi)]$$

- For a moment assume ρ_0 to be constant. Then ignoring the lower order terms, we pull T^* out of the equation to get

$$\partial_t^2(\rho_0 \varphi) = c^2 \rho_0^{-1} T T^*(\rho_0 \varphi) = \underbrace{c^2 \Delta}_{\Delta_c}(\rho_0 \varphi) + \text{l.o.t.}$$

Extracting the Laplacian

- neglecting the Coriolis term and the lower-order terms the acousto-gravitational system becomes

$$\partial_t^2(\rho_0 u) = \nabla[c^2(\nabla \cdot (\rho_0 u) - \tilde{s} \cdot u)] = \nabla[c^2 T u]$$

- we use the generalized Helmholtz decomposition (Lemma 2 in the first lecture) to write $u = T^*(\rho_0 \varphi) + u_2$ with $\varphi \in H^1(M)$ and $u_2 \in \text{Ker}(T)$; the equation becomes

$$\partial_t^2(T^*(\rho_0 \varphi)) + \partial_t^2 u_2 = \rho_0^{-1} \nabla[c^2 T T^*(\rho_0 \varphi)].$$

- setting $u_2 = 0$ and replacing ∇ with T^* to obtain

$$\partial_t^2(T^*(\rho_0 \varphi)) = \rho_0^{-1} T^*[c^2 T T^*(\rho_0 \varphi)]$$

- For a moment assume ρ_0 to be constant. Then ignoring the lower order terms, we pull T^* out of the equation to get

$$\partial_t^2(\rho_0 \varphi) = c^2 \rho_0^{-1} T T^*(\rho_0 \varphi) = \underbrace{c^2 \Delta}_{\Delta_c}(\rho_0 \varphi) + \text{l.o.t.}$$

Extracting the Laplacian

- neglecting the Coriolis term and the lower-order terms the acousto-gravitational system becomes

$$\partial_t^2(\rho_0 u) = \nabla[c^2(\nabla \cdot (\rho_0 u) - \tilde{s} \cdot u)] = \nabla[c^2 T u]$$

- we use the generalized Helmholtz decomposition (Lemma 2 in the first lecture) to write $u = T^*(\rho_0 \varphi) + u_2$ with $\varphi \in H^1(M)$ and $u_2 \in \text{Ker}(T)$; the equation becomes

$$\partial_t^2(T^*(\rho_0 \varphi)) + \partial_t^2 u_2 = \rho_0^{-1} \nabla[c^2 T T^*(\rho_0 \varphi)].$$

- setting $u_2 = 0$ and replacing ∇ with T^* to obtain

$$\partial_t^2(T^*(\rho_0 \varphi)) = \rho_0^{-1} T^*[c^2 T T^*(\rho_0 \varphi)]$$

- For a moment assume ρ_0 to be constant. Then ignoring the lower order terms, we pull T^* out of the equation to get

$$\partial_t^2(\rho_0 \varphi) = c^2 \rho_0^{-1} T T^*(\rho_0 \varphi) = \underbrace{c^2 \Delta}_{\Delta_c}(\rho_0 \varphi) + \text{l.o.t.}$$

Extracting the Laplacian

- neglecting the Coriolis term and the lower-order terms the acousto-gravitational system becomes

$$\partial_t^2(\rho_0 u) = \nabla[c^2(\nabla \cdot (\rho_0 u) - \tilde{s} \cdot u)] = \nabla[c^2 T u]$$

- we use the generalized Helmholtz decomposition (Lemma 2 in the first lecture) to write $u = T^*(\rho_0 \varphi) + u_2$ with $\varphi \in H^1(M)$ and $u_2 \in \text{Ker}(T)$; the equation becomes

$$\partial_t^2(T^*(\rho_0 \varphi)) + \partial_t^2 u_2 = \rho_0^{-1} \nabla[c^2 T T^*(\rho_0 \varphi)].$$

- setting $u_2 = 0$ and replacing ∇ with T^* to obtain

$$\partial_t^2(T^*(\rho_0 \varphi)) = \rho_0^{-1} T^*[c^2 T T^*(\rho_0 \varphi)]$$

- For a moment assume ρ_0 to be constant. Then ignoring the lower order terms, we pull T^* out of the equation to get

$$\partial_t^2(\rho_0 \varphi) = c^2 \rho_0^{-1} T T^*(\rho_0 \varphi) = \underbrace{c^2 \Delta}_{\Delta_c}(\rho_0 \varphi) + \text{l.o.t.}$$

Riemannian setting

The Laplacian Δ_c is really the Laplace-Beltrami operator of the Riemannian metric $c^{-2}\text{Id}_{n \times n}$.

Consider a bounded smooth domain $\Omega \subseteq \mathbb{R}^n$. We use coordinates (x, y) in a neighborhood of the boundary where $\partial\Omega = \{x = 0\}$ and $y = (y_1, \dots, y_{n-1})$ are coordinates on $\partial\Omega$.

Generalized setting: Replace the conformal sound speed by an anisotropic one, represented as a Riemannian metric g . The vanishing of the sound speed forces the metric to be of the form

$$g = \frac{\bar{g}}{x^\alpha} = \frac{dx^2 + h_{ij}(x, y)dy^i dy^j}{x^\alpha}$$

where $\alpha \in (0, 2)$ and \bar{g} is a Riemannian metric that is smooth up to and including $\partial\Omega$ and $h(x, \cdot)$ is a family of Riemannian metrics on $\partial\Omega$.

The geometry of g is called **gas giant geometry**.

Riemannian setting

The Laplacian Δ_c is really the Laplace-Beltrami operator of the Riemannian metric $c^{-2}\text{Id}_{n \times n}$.

Consider a bounded smooth domain $\Omega \subseteq \mathbb{R}^n$. We use coordinates (x, y) in a neighborhood of the boundary where $\partial\Omega = \{x = 0\}$ and $y = (y_1, \dots, y_{n-1})$ are coordinates on $\partial\Omega$.

Generalized setting: Replace the conformal sound speed by an anisotropic one, represented as a Riemannian metric g . The vanishing of the sound speed forces the metric to be of the form

$$g = \frac{\bar{g}}{x^\alpha} = \frac{dx^2 + h_{ij}(x, y)dy^i dy^j}{x^\alpha}$$

where $\alpha \in (0, 2)$ and \bar{g} is a Riemannian metric that is smooth up to and including $\partial\Omega$ and $h(x, \cdot)$ is a family of Riemannian metrics on $\partial\Omega$.

The geometry of g is called **gas giant geometry**.

Riemannian setting

The Laplacian Δ_c is really the Laplace-Beltrami operator of the Riemannian metric $c^{-2}\text{Id}_{n \times n}$.

Consider a bounded smooth domain $\Omega \subseteq \mathbb{R}^n$. We use coordinates (x, y) in a neighborhood of the boundary where $\partial\Omega = \{x = 0\}$ and $y = (y_1, \dots, y_{n-1})$ are coordinates on $\partial\Omega$.

Generalized setting: Replace the conformal sound speed by an anisotropic one, represented as a Riemannian metric g . The vanishing of the sound speed forces the metric to be of the form

$$g = \frac{\bar{g}}{x^\alpha} = \frac{dx^2 + h_{ij}(x, y)dy^i dy^j}{x^\alpha}$$

where $\alpha \in (0, 2)$ and \bar{g} is a Riemannian metric that is smooth up to and including $\partial\Omega$ and $h(x, \cdot)$ is a family of Riemannian metrics on $\partial\Omega$.

The geometry of g is called **gas giant geometry**.

Riemannian setting

The Laplacian Δ_c is really the Laplace-Beltrami operator of the Riemannian metric $c^{-2}\text{Id}_{n \times n}$.

Consider a bounded smooth domain $\Omega \subseteq \mathbb{R}^n$. We use coordinates (x, y) in a neighborhood of the boundary where $\partial\Omega = \{x = 0\}$ and $y = (y_1, \dots, y_{n-1})$ are coordinates on $\partial\Omega$.

Generalized setting: Replace the conformal sound speed by an anisotropic one, represented as a Riemannian metric g . The vanishing of the sound speed forces the metric to be of the form

$$g = \frac{\bar{g}}{x^\alpha} = \frac{dx^2 + h_{ij}(x, y)dy^i dy^j}{x^\alpha}$$

where $\alpha \in (0, 2)$ and \bar{g} is a Riemannian metric that is smooth up to and including $\partial\Omega$ and $h(x, \cdot)$ is a family of Riemannian metrics on $\partial\Omega$.

The geometry of g is called **gas giant geometry**.

Degenerate Laplacian

The Laplace-Beltrami operator of the gas giant metric $g(x, y)$ is

$$\Delta_g u = \sum_{i,j} \frac{1}{\sqrt{\det(g)}} \partial_i \left(\sqrt{\det(g)} g_{ij}^{-1} \partial_j u \right).$$

To derive a more manageable formula for Δ_g we use the fact that $\det(g) = x^{-\alpha n} \det(\bar{g})$. Then, using the fact that $\bar{g}_{00} = 1$ and $\bar{g}_{0i} = 0$ for $i \neq 0$, we obtain

$$\begin{aligned} \Delta_g u &= \sum_{i,j} \frac{x^{\alpha \frac{n}{2}}}{\sqrt{\det(\bar{g})}} \partial_i \left(x^{\alpha(1-\frac{n}{2})} \sqrt{\det(\bar{g})} \bar{g}_{ij}^{-1} \partial_j u \right) \\ &= \frac{x^{\alpha \frac{n}{2}}}{\sqrt{\det(\bar{g})}} \left[\partial_x \left(x^{\alpha(1-\frac{n}{2})} \sqrt{\det(\bar{g})} \partial_x u \right) + \sum_{i,j} \partial_{y_i} \left(x^{\alpha(1-\frac{n}{2})} \sqrt{\det(\bar{g})} \bar{g}_{ij}^{-1} \partial_{y_j} u \right) \right] \\ &= x^\alpha \Delta_{\bar{g}} u + \alpha \left(1 - \frac{n}{2} \right) x^{\alpha-1} \partial_x u. \end{aligned}$$

Degenerate Laplacian

The Laplace-Beltrami operator of the gas giant metric $g(x, y)$ is

$$\Delta_g u = \sum_{i,j} \frac{1}{\sqrt{\det(g)}} \partial_i \left(\sqrt{\det(g)} g_{ij}^{-1} \partial_j u \right).$$

To derive a more manageable formula for Δ_g we use the fact that $\det(g) = x^{-\alpha n} \det(\bar{g})$. Then, using the fact that $\bar{g}_{00} = 1$ and $\bar{g}_{0i} = 0$ for $i \neq 0$, we obtain

$$\begin{aligned} \Delta_g u &= \sum_{i,j} \frac{x^{\alpha \frac{n}{2}}}{\sqrt{\det(\bar{g})}} \partial_i \left(x^{\alpha(1-\frac{n}{2})} \sqrt{\det(\bar{g})} \bar{g}_{ij}^{-1} \partial_j u \right) \\ &= \frac{x^{\alpha \frac{n}{2}}}{\sqrt{\det(\bar{g})}} \left[\partial_x \left(x^{\alpha(1-\frac{n}{2})} \sqrt{\det(\bar{g})} \partial_x u \right) + \sum_{i,j} \partial_{y_i} \left(x^{\alpha(1-\frac{n}{2})} \sqrt{\det(\bar{g})} \bar{g}_{ij}^{-1} \partial_{y_j} u \right) \right] \\ &= x^\alpha \Delta_{\bar{g}} u + \alpha \left(1 - \frac{n}{2} \right) x^{\alpha-1} \partial_x u. \end{aligned}$$

Uniformly degenerate partial differential operators

The Laplace-Beltrami operator is degenerate at $\{x = 0\}$, but the degeneracy is uniform in the basic vector fields $x\partial_x$ and $x\partial_{y_k}$. In particular, after multiplying with the power $x^{2-\alpha}$ we get

$$\begin{aligned} x^{2-\alpha}\Delta_g &= (x\partial_x)^2u + \det(\bar{g})^{-1/2}[(x\partial_x)\det(\bar{g})^{1/2}][(x\partial_x)u] \\ &\quad + \det(\bar{g})^{-1/2}\sum_{i,j}(x\partial_{y_i})(\det(\bar{g})^{1/2}\bar{g}_{ij}^{-1}(x\partial_{y_j})u). \end{aligned}$$

In general, a **0-differential operator** P of order m is of the form

$$P = \sum_{i+|\beta|\leq m} a_{i,\beta}(x,y)(x\partial_x)^i(x\partial_{y_\beta})^\beta \tag{2}$$

where $a_{i,\beta}(x,y)$ are smooth functions. Clearly $x^{2-\alpha}\Delta_g$ is a 0-differential operator of order 2.

Uniformly degenerate partial differential operators

The Laplace-Beltrami operator is degenerate at $\{x = 0\}$, but the degeneracy is uniform in the basic vector fields $x\partial_x$ and $x\partial_{y_k}$. In particular, after multiplying with the power $x^{2-\alpha}$ we get

$$\begin{aligned} x^{2-\alpha}\Delta_g &= (x\partial_x)^2u + \det(\bar{g})^{-1/2}[(x\partial_x)\det(\bar{g})^{1/2}][(x\partial_x)u] \\ &\quad + \det(\bar{g})^{-1/2}\sum_{i,j}(x\partial_{y_i})(\det(\bar{g})^{1/2}\bar{g}_{ij}^{-1}(x\partial_{y_j})u). \end{aligned}$$

In general, a **0-differential operator** P of order m is of the form

$$P = \sum_{i+|\beta|\leq m} a_{i,\beta}(x,y)(x\partial_x)^i(x\partial_{y_\beta})^\beta \tag{2}$$

where $a_{i,\beta}(x,y)$ are smooth functions. Clearly $x^{2-\alpha}\Delta_g$ is a 0-differential operator of order 2.

A brief introduction to 0-calculus

A more detailed exposition on the basics of 0-calculus can be found in [Maz91].

The **indicial operator** of the 0-differential operator P in (2) is

$$I(P) = \sum_{i \leq m} a_{i,0}(0, y) (x \partial_x)^i.$$

In particular, for the Laplacian $L = x^{2-\alpha} \Delta_g$,

$$I(L) = (x \partial_x)^2 - \alpha \left(\frac{n}{2} - 1 \right) (x \partial_x).$$

We will use the indicial operator $I(L)$ momentarily to compute an invariant called **indicial roots** (the indicial operator fails to be invertible).

Associated to a 0-differential operator P is its 0-**principal symbol** ${}^0\sigma_m(P)$, which is obtained by replacing $x \partial_x$ and $x \partial_{y_k}$ with ξ and η_k in the local presentation of the operator.

A brief introduction to 0-calculus

A more detailed exposition on the basics of 0-calculus can be found in [Maz91].

The **indicial operator** of the 0-differential operator P in (2) is

$$I(P) = \sum_{i \leq m} a_{i,0}(0, y) (x \partial_x)^i.$$

In particular, for the Laplacian $L = x^{2-\alpha} \Delta_g$,

$$I(L) = (x \partial_x)^2 - \alpha \left(\frac{n}{2} - 1 \right) (x \partial_x).$$

We will use the indicial operator $I(L)$ momentarily to compute an invariant called **indicial roots** (the indicial operator fails to be invertible).

Associated to a 0-differential operator P is its 0-**principal symbol** ${}^0\sigma_m(P)$, which is obtained by replacing $x \partial_x$ and $x \partial_{y_k}$ with ξ and η_k in the local presentation of the operator.

A brief introduction to 0-calculus

A more detailed exposition on the basics of 0-calculus can be found in [Maz91].

The **indicial operator** of the 0-differential operator P in (2) is

$$I(P) = \sum_{i \leq m} a_{i,0}(0, y) (x \partial_x)^i.$$

In particular, for the Laplacian $L = x^{2-\alpha} \Delta_g$,

$$I(L) = (x \partial_x)^2 - \alpha \left(\frac{n}{2} - 1 \right) (x \partial_x).$$

We will use the indicial operator $I(L)$ momentarily to compute an invariant called **indicial roots** (the indicial operator fails to be invertible).

Associated to a 0-differential operator P is its 0-**principal symbol** ${}^0\sigma_m(P)$, which is obtained by replacing $x \partial_x$ and $x \partial_{y_k}$ with ξ and η_k in the local presentation of the operator.

A brief introduction to 0-calculus

In symbols, the 0-principal symbol is

$$P = \sum_{i+\beta \leq m} a_{i,\beta}(x, y) (x\partial_x)^i (x\partial_{y_\beta})^\beta \Rightarrow {}^0\sigma_m(P) = \sum_{i+\beta=m} a_{i,\beta}(x, y) \xi^i \eta^\beta.$$

An operator is **0-elliptic**, if its principal symbol is non-vanishing when $(\xi, \eta) \neq (0, 0)$.

Recalling that $\bar{g}_{ij} = h_{ij}$ when $i, j \neq 0$, the 0-principal symbol of the Laplacian L is

$${}^0\sigma_2(L) = \xi^2 + \sum_{i,j \neq 0} h_{ij}^{-1}(x, y) \eta_i \eta_j = \xi^2 + |\eta|_h^2.$$

Hence L is 0-elliptic. As such, the calculus of 0-pseudodifferential operators offers analogues of all the familiar constructions in [pseudodifferential theory](#).

There is an [elliptic parametrix construction](#) for L , and the various properties of the parametrix G for L obtained through this construction lead to sharp mapping and regularity properties.

A brief introduction to 0-calculus

In symbols, the 0-principal symbol is

$$P = \sum_{i+\beta \leq m} a_{i,\beta}(x, y) (x\partial_x)^i (x\partial_{y_\beta})^\beta \Rightarrow {}^0\sigma_m(P) = \sum_{i+\beta=m} a_{i,\beta}(x, y) \xi^i \eta^\beta.$$

An operator is **0-elliptic**, if its principal symbol is non-vanishing when $(\xi, \eta) \neq (0, 0)$.

Recalling that $\bar{g}_{ij} = h_{ij}$ when $i, j \neq 0$, the 0-principal symbol of the Laplacian L is

$${}^0\sigma_2(L) = \xi^2 + \sum_{i,j \neq 0} h_{ij}^{-1}(x, y) \eta_i \eta_j = \xi^2 + |\eta|_h^2.$$

Hence L is 0-elliptic. As such, the calculus of 0-pseudodifferential operators offers analogues of all the familiar constructions in [pseudodifferential theory](#).

There is an [elliptic parametrix construction](#) for L , and the various properties of the parametrix G for L obtained through this construction lead to sharp mapping and regularity properties.

A brief introduction to 0-calculus

In symbols, the 0-principal symbol is

$$P = \sum_{i+\beta \leq m} a_{i,\beta}(x, y) (x\partial_x)^i (x\partial_{y_\beta})^\beta \Rightarrow {}^0\sigma_m(P) = \sum_{i+\beta=m} a_{i,\beta}(x, y) \xi^i \eta^\beta.$$

An operator is **0-elliptic**, if its principal symbol is non-vanishing when $(\xi, \eta) \neq (0, 0)$.

Recalling that $\bar{g}_{ij} = h_{ij}$ when $i, j \neq 0$, the 0-principal symbol of the Laplacian L is

$${}^0\sigma_2(L) = \xi^2 + \sum_{i,j \neq 0} h_{ij}^{-1}(x, y) \eta_i \eta_j = \xi^2 + |\eta|_h^2.$$

Hence L is 0-elliptic. As such, the calculus of 0-pseudodifferential operators offers analogues of all the familiar constructions in [pseudodifferential theory](#).

There is an [elliptic parametrix construction](#) for L , and the various properties of the parametrix G for L obtained through this construction lead to sharp mapping and regularity properties.

A brief introduction to 0-calculus

- in slightly more detail, parametrices of 0-differential operators are 0-pseudodifferential operators, which are usually defined on the level of their Schwartz kernels
- the Schwartz kernel of a 0-pseudodifferential operator has conormal singularities on the diagonal and are smooth elsewhere, the same as classical pseudodifferential operators
- The difference is what happens at the boundary of the domain, which classical theory does not account for
- **roughly** speaking, the Schwartz kernel of a 0-pseudodifferential operator has **polyhomogeneous** conormal behavior at the boundary hypersurfaces $\partial\Omega \times \Omega$, $\Omega \times \partial\Omega$ and the front face
- the part here that is **rough** is that the natural space for the Schwartz kernel is a 0-double tangent space obtained blowing up the boundary diagonal $\text{diag}(\partial\Omega \times \partial\Omega)$ in $\Omega \times \Omega$
- **polyhomogeneity** means that there are expansions into asymptotic sums of terms $x^z (\log x)^k a_{z,k}(y)$ when $\{x = 0\}$ defines a boundary hypersurface

A brief introduction to 0-calculus

- in slightly more detail, parametrices of 0-differential operators are 0-pseudodifferential operators, which are usually defined on the level of their Schwartz kernels
- the Schwartz kernel of a 0-pseudodifferential operator has conormal singularities on the diagonal and are smooth elsewhere, the same as classical pseudodifferential operators
- The difference is what happens at the boundary of the domain, which classical theory does not account for
- **roughly** speaking, the Schwartz kernel of a 0-pseudodifferential operator has **polyhomogeneous** conormal behavior at the boundary hypersurfaces $\partial\Omega \times \Omega$, $\Omega \times \partial\Omega$ and the front face
- the part here that is **rough** is that the natural space for the Schwartz kernel is a 0-double tangent space obtained blowing up the boundary diagonal $\text{diag}(\partial\Omega \times \partial\Omega)$ in $\Omega \times \Omega$
- **polyhomogeneity** means that there are expansions into asymptotic sums of terms $x^z (\log x)^k a_{z,k}(y)$ when $\{x = 0\}$ defines a boundary hypersurface

A brief introduction to 0-calculus

- in slightly more detail, parametrices of 0-differential operators are 0-pseudodifferential operators, which are usually defined on the level of their Schwartz kernels
- the Schwartz kernel of a 0-pseudodifferential operator has conormal singularities on the diagonal and are smooth elsewhere, the same as classical pseudodifferential operators
- The difference is what happens at the boundary of the domain, which classical theory does not account for
- **roughly** speaking, the Schwartz kernel of a 0-pseudodifferential operator has **polyhomogeneous** conormal behavior at the boundary hypersurfaces $\partial\Omega \times \Omega$, $\Omega \times \partial\Omega$ and the front face
- the part here that is **rough** is that the natural space for the Schwartz kernel is a 0-double tangent space obtained blowing up the boundary diagonal $\text{diag}(\partial\Omega \times \partial\Omega)$ in $\Omega \times \Omega$
- **polyhomogeneity** means that there are expansions into asymptotic sums of terms $x^z (\log x)^k a_{z,k}(y)$ when $\{x = 0\}$ defines a boundary hypersurface

A brief introduction to 0-calculus

- in slightly more detail, parametrices of 0-differential operators are 0-pseudodifferential operators, which are usually defined on the level of their Schwartz kernels
- the Schwartz kernel of a 0-pseudodifferential operator has conormal singularities on the diagonal and are smooth elsewhere, the same as classical pseudodifferential operators
- The difference is what happens at the boundary of the domain, which classical theory does not account for
- **roughly** speaking, the Schwartz kernel of a 0-pseudodifferential operator has **polyhomogeneous** conormal behavior at the boundary hypersurfaces $\partial\Omega \times \Omega$, $\Omega \times \partial\Omega$ and the front face
- the part here that is **rough** is that the natural space for the Schwartz kernel is a 0-double tangent space obtained blowing up the boundary diagonal $\text{diag}(\partial\Omega \times \partial\Omega)$ in $\Omega \times \Omega$
- **polyhomogeneity** means that there are expansions into asymptotic sums of terms $x^z (\log x)^k a_{z,k}(y)$ when $\{x = 0\}$ defines a boundary hypersurface

A brief introduction to 0-calculus

- in slightly more detail, parametrices of 0-differential operators are 0-pseudodifferential operators, which are usually defined on the level of their Schwartz kernels
- the Schwartz kernel of a 0-pseudodifferential operator has conormal singularities on the diagonal and are smooth elsewhere, the same as classical pseudodifferential operators
- The difference is what happens at the boundary of the domain, which classical theory does not account for
- **roughly** speaking, the Schwartz kernel of a 0-pseudodifferential operator has **polyhomogeneous** conormal behavior at the boundary hypersurfaces $\partial\Omega \times \Omega$, $\Omega \times \partial\Omega$ and the front face
- the part here that is **rough** is that the natural space for the Schwartz kernel is a 0-double tangent space obtained blowing up the boundary diagonal $\text{diag}(\partial\Omega \times \partial\Omega)$ in $\Omega \times \Omega$
- **polyhomogeneity** means that there are expansions into asymptotic sums of terms $x^z (\log x)^k a_{z,k}(y)$ when $\{x = 0\}$ defines a boundary hypersurface

A brief introduction to 0-calculus

- in slightly more detail, parametrices of 0-differential operators are 0-pseudodifferential operators, which are usually defined on the level of their Schwartz kernels
- the Schwartz kernel of a 0-pseudodifferential operator has conormal singularities on the diagonal and are smooth elsewhere, the same as classical pseudodifferential operators
- The difference is what happens at the boundary of the domain, which classical theory does not account for
- **roughly** speaking, the Schwartz kernel of a 0-pseudodifferential operator has **polyhomogeneous** conormal behavior at the boundary hypersurfaces $\partial\Omega \times \Omega$, $\Omega \times \partial\Omega$ and the front face
- the part here that is **rough** is that the natural space for the Schwartz kernel is a 0-double tangent space obtained blowing up the boundary diagonal $\text{diag}(\partial\Omega \times \partial\Omega)$ in $\Omega \times \Omega$
- **polyhomogeneity** means that there are expansions into asymptotic sums of terms $x^z (\log x)^k a_{z,k}(y)$ when $\{x = 0\}$ defines a boundary hypersurface

A brief introduction to 0-calculus

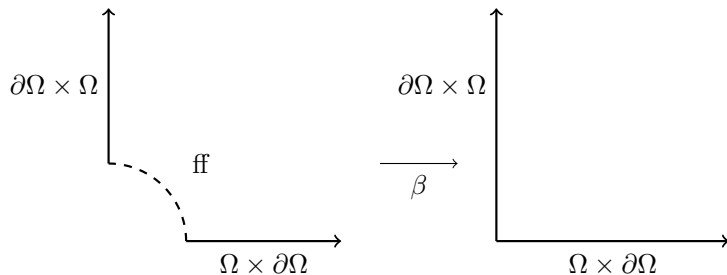


Figure 1: An example of a blow-up: Here $\Omega = [0, \infty)$ and on the left we have blown up the boundary diagonal in $\Omega \times \Omega$, i.e., the origin. This corresponds to introduction of polar coordinates β around $(0, 0)$. Pseudodifferential operator in the 0-calculus have polyhomogeneous asymptotics at $\Omega \times \partial\Omega$, $\partial\Omega \times \Omega$ and the front face ff .

Self-adjointness

Consider the densely defined unbounded operator

$$\Delta_g: L^2(\Omega, dV_g) \longrightarrow L^2(\Omega, dV_g). \quad (3)$$

This is symmetric on the core domain $C_0^\infty(\Omega)$ of smooth functions compactly supported in the interior.

Before studying the spectrum of Δ_g we need to determine whether Δ_g has a unique self-adjoint extension, or if boundary conditions need to be imposed to obtain a self-adjoint realization.

This is where we need to compute the **indicial roots** of Δ_g . The pair of indicial roots, γ_\pm , are the values of γ so that $I(x^{2-\alpha}\Delta_g)x^\gamma = 0$ (the indicial operator fails to be invertible). These are the exponents which yield approximate solutions in the sense that

$$\Delta_g x^\gamma = \mathcal{O}(x^{\gamma-1+\alpha})$$

rather than the expected rate $\mathcal{O}(x^{\gamma-2+\alpha})$, i.e., there is leading order cancellation.

Self-adjointness

Consider the densely defined unbounded operator

$$\Delta_g: L^2(\Omega, dV_g) \longrightarrow L^2(\Omega, dV_g). \quad (3)$$

This is symmetric on the core domain $C_0^\infty(\Omega)$ of smooth functions compactly supported in the interior.

Before studying the spectrum of Δ_g we need to determine whether Δ_g has a unique self-adjoint extension, or if boundary conditions need to be imposed to obtain a self-adjoint realization.

This is where we need to compute the **indicial roots** of Δ_g . The pair of indicial roots, γ_\pm , are the values of γ so that $I(x^{2-\alpha}\Delta_g)x^\gamma = 0$ (the indicial operator fails to be invertible). These are the exponents which yield approximate solutions in the sense that

$$\Delta_g x^\gamma = \mathcal{O}(x^{\gamma-1+\alpha})$$

rather than the expected rate $\mathcal{O}(x^{\gamma-2+\alpha})$, i.e., there is leading order cancellation.

Self-adjointness

Consider the densely defined unbounded operator

$$\Delta_g: L^2(\Omega, dV_g) \longrightarrow L^2(\Omega, dV_g). \quad (3)$$

This is symmetric on the core domain $C_0^\infty(\Omega)$ of smooth functions compactly supported in the interior.

Before studying the spectrum of Δ_g we need to determine whether Δ_g has a unique self-adjoint extension, or if boundary conditions need to be imposed to obtain a self-adjoint realization.

This is where we need to compute the **indicial roots** of Δ_g . The pair of indicial roots, γ_\pm , are the values of γ so that $I(x^{2-\alpha}\Delta_g)x^\gamma = 0$ (the indicial operator fails to be invertible). These are the exponents which yield approximate solutions in the sense that

$$\Delta_g x^\gamma = \mathcal{O}(x^{\gamma-1+\alpha})$$

rather than the expected rate $\mathcal{O}(x^{\gamma-2+\alpha})$, i.e., there is leading order cancellation.

Self-adjointness and indicial roots

To calculate the indicial roots, we compute

$$\Delta_g x^\gamma = (\gamma(\gamma - 1) - \alpha(n/2 - 1)\gamma) x^{\gamma-2+\alpha} + \mathcal{O}(x^{\gamma-1+\alpha}),$$

and hence γ must satisfy $\gamma^2 - (\alpha(n/2 - 1) + 1)\gamma = 0$, or

$$\begin{aligned}\gamma_\pm &= 0, \alpha(n/2 - 1) + 1 \\ &= \frac{1}{2}(\alpha(n/2 - 1) + 1) \pm \frac{1}{2}(\alpha(n/2 - 1) + 1).\end{aligned}$$

This last expression is included to emphasize the symmetry of γ_\pm around their average, which is useful below.

Self-adjointness and indicial roots

Next, observe that a function x^γ lies in $L^2(dV_g)$ near $x = 0$ if and only if

$$\gamma > \frac{1}{2}(n\alpha/2 - 1).$$

We call this threshold the “ L^2 cutoff weight”. Recall $dV_g = x^{-\alpha\frac{n}{2}} dx dV_h$.

It is most natural to let Δ_g act on the Sobolev spaces adapted to the 0-vector fields:

$$H_0^k(\Omega, dV_g) = \{u : V_1 \dots V_\ell u \in L^2(dV_g) \quad \ell \leq k, \quad \text{each } V_i \in \mathcal{V}_0(\Omega)\},$$

and their weighted version $x^\mu H_0^k = \{u = x^\mu v : v \in H_0^k\}$.

Here the space of 0-vector fields $\mathcal{V}_0(\Omega)$ is simply the set of smooth linear combinations of the derivatives $x\partial_x$ and $x\partial_{y_j}$.

Self-adjointness and indicial roots

Next, observe that a function x^γ lies in $L^2(dV_g)$ near $x = 0$ if and only if

$$\gamma > \frac{1}{2}(n\alpha/2 - 1).$$

We call this threshold the “ L^2 cutoff weight”. Recall $dV_g = x^{-\alpha\frac{n}{2}} dx dV_h$.

It is most natural to let Δ_g act on the Sobolev spaces adapted to the **0-vector fields**:

$$H_0^k(\Omega, dV_g) = \{u : V_1 \dots V_\ell u \in L^2(dV_g) \quad \ell \leq k, \quad \text{each } V_i \in \mathcal{V}_0(\Omega)\},$$

and their weighted version $x^\mu H_0^k = \{u = x^\mu v : v \in H_0^k\}$.

Here the space of **0-vector fields** $\mathcal{V}_0(\Omega)$ is simply the set of smooth linear combinations of the derivatives $x\partial_x$ and $x\partial_{y_j}$.

Self-adjointness and indicial roots

It is clear from this definition that

$$\Delta_g: x^\mu H_0^2 \longrightarrow x^{\mu-2+\alpha} L^2$$

is bounded for every μ . In particular, $\Delta_g u \in L^2$ if $u \in x^\mu H_0^2$ where $\mu \geq 2 - \alpha$.

Since $C_0^\infty(\Omega)$ is dense in $x^{2-\alpha} H_0^2$, it is clear that the minimal domain, i.e., the minimal closed extension from the core domain, of (3) is contained in $x^{2-\alpha} H_0^2$.

Using the parametrix for Δ_g alluded to above, it can be proved that this is an equality:

$$\mathcal{D}_{\min}(\Delta_g) = x^{2-\alpha} H_0^2(\Omega, dV_g).$$

On the other hand, we also define the maximal domain $\mathcal{D}_{\max}(\Delta_g) = \{u \in L^2 : \Delta_g u \in L^2\}$.

Self-adjointness and indicial roots

It is clear from this definition that

$$\Delta_g: x^\mu H_0^2 \longrightarrow x^{\mu-2+\alpha} L^2$$

is bounded for every μ . In particular, $\Delta_g u \in L^2$ if $u \in x^\mu H_0^2$ where $\mu \geq 2 - \alpha$.

Since $C_0^\infty(\Omega)$ is dense in $x^{2-\alpha} H_0^2$, it is clear that the minimal domain, i.e., the minimal closed extension from the core domain, of (3) is contained in $x^{2-\alpha} H_0^2$.

Using the parametrix for Δ_g alluded to above, it can be proved that this is an equality:

$$\mathcal{D}_{\min}(\Delta_g) = x^{2-\alpha} H_0^2(\Omega, dV_g).$$

On the other hand, we also define the maximal domain $\mathcal{D}_{\max}(\Delta_g) = \{u \in L^2 : \Delta_g u \in L^2\}$.

Self-adjointness and indicial roots

It is clear from this definition that

$$\Delta_g: x^\mu H_0^2 \longrightarrow x^{\mu-2+\alpha} L^2$$

is bounded for every μ . In particular, $\Delta_g u \in L^2$ if $u \in x^\mu H_0^2$ where $\mu \geq 2 - \alpha$.

Since $C_0^\infty(\Omega)$ is dense in $x^{2-\alpha} H_0^2$, it is clear that the minimal domain, i.e., the minimal closed extension from the core domain, of (3) is contained in $x^{2-\alpha} H_0^2$.

Using the parametrix for Δ_g alluded to above, it can be proved that this is an equality:

$$\mathcal{D}_{\min}(\Delta_g) = x^{2-\alpha} H_0^2(\Omega, dV_g).$$

On the other hand, we also define the maximal domain $\mathcal{D}_{\max}(\Delta_g) = \{u \in L^2 : \Delta_g u \in L^2\}$.

Proposition 1 (Self-adjointness)

The operator Δ_g is essentially self-adjoint on L^2 , i.e.,

$$\mathcal{D}_{\min}(\Delta_g) = \mathcal{D}_{\max}(\Delta_g)$$

if and only if $\alpha > 2/n$.

The value $\alpha = 2/n$ is precisely the critical value where the Riemannian volume of M becomes infinite: $\text{Vol}_g(\Omega) < \infty$ iff $\alpha < 2/n$.

Proof of Proposition 1

- the key issue is whether either of the indicial roots γ_{\pm} lie in the critical weight interval

$$\mu_- := \frac{1}{2}(n\alpha/2 - 1) \leq \mu \leq \frac{1}{2}(n\alpha/2 - 1) + 2 - \alpha =: \mu_+$$

- the relevance of whether the indicial roots are included in the critical weight interval is that, using the parametrix carefully, one can deduce that if γ_{\pm} do not lie in this critical weight interval, then $u \in L^2$ and $\Delta_g u \in L^2$ imply that $u \in x^{2-\alpha} H_0^2 = \mathcal{D}_{\min}$
- notice that the midpoint of this critical interval is

$$\frac{1}{2}(n\alpha/2 - 1) + 1 - \frac{1}{2}\alpha = \frac{1}{2}(\alpha(n/2 - 1) + 1)$$

which is precisely the same as the midpoint of the gap between the two indicial roots.

Proof of Proposition 1

- the key issue is whether either of the indicial roots γ_{\pm} lie in the critical weight interval

$$\mu_- := \frac{1}{2}(n\alpha/2 - 1) \leq \mu \leq \frac{1}{2}(n\alpha/2 - 1) + 2 - \alpha =: \mu_+$$

- the relevance of whether the indicial roots are included in the critical weight interval is that, using the parametrix carefully, one can deduce that if γ_{\pm} do not lie in this critical weight interval, then $u \in L^2$ and $\Delta_g u \in L^2$ imply that $u \in x^{2-\alpha} H_0^2 = \mathcal{D}_{\min}$
- notice that the midpoint of this critical interval is

$$\frac{1}{2}(n\alpha/2 - 1) + 1 - \frac{1}{2}\alpha = \frac{1}{2}(\alpha(n/2 - 1) + 1)$$

which is precisely the same as the midpoint of the gap between the two indicial roots.

Proof of Proposition 1

- the key issue is whether either of the indicial roots γ_{\pm} lie in the critical weight interval

$$\mu_- := \frac{1}{2}(n\alpha/2 - 1) \leq \mu \leq \frac{1}{2}(n\alpha/2 - 1) + 2 - \alpha =: \mu_+$$

- the relevance of whether the indicial roots are included in the critical weight interval is that, using the parametrix carefully, one can deduce that if γ_{\pm} do not lie in this critical weight interval, then $u \in L^2$ and $\Delta_g u \in L^2$ imply that $u \in x^{2-\alpha} H_0^2 = \mathcal{D}_{\min}$
- notice that the midpoint of this critical interval is

$$\frac{1}{2}(n\alpha/2 - 1) + 1 - \frac{1}{2}\alpha = \frac{1}{2}(\alpha(n/2 - 1) + 1)$$

which is precisely the same as the midpoint of the gap between the two indicial roots.

Proof of Proposition 1

- the key issue is whether either of the indicial roots γ_{\pm} lie in the critical weight interval

$$\mu_- := \frac{1}{2}(n\alpha/2 - 1) \leq \mu \leq \frac{1}{2}(n\alpha/2 - 1) + 2 - \alpha =: \mu_+$$

- the relevance of whether the indicial roots are included in the critical weight interval is that, using the parametrix carefully, one can deduce that if γ_{\pm} do not lie in this critical weight interval, then $u \in L^2$ and $\Delta_g u \in L^2$ imply that $u \in x^{2-\alpha} H_0^2 = \mathcal{D}_{\min}$
- notice that the midpoint of this critical interval is

$$\frac{1}{2}(n\alpha/2 - 1) + 1 - \frac{1}{2}\alpha = \frac{1}{2}(\alpha(n/2 - 1) + 1)$$

which is precisely the same as the midpoint of the gap between the two indicial roots.

Proof of Proposition 1

- the width of this weight interval is $2 - \alpha$, whereas $\gamma_+ - \gamma_- = \alpha(n/2 - 1) + 1$. We claim that

$$\gamma_- < \mu_- < \mu_+ < \gamma_+$$

precisely when $\alpha > 2/n$, which is verified by noting that $\alpha(n/2 - 1) + 1 > 2 - \alpha$ precisely then

- however, when $\alpha \leq 2/n$, then we can only deduce that

$$u(x, y) \sim \sum a_j(y) x^{\gamma_- + j} + \sum b_j(y) x^{\gamma_+ + j} \quad (4)$$

- this asymptotic expansion has some complicating features, such as that if $a_0 \neq 0$, then the coefficients a_j, b_j may only have finite regularity (and will have negative Sobolev regularity for large j)
- conversely, there exists a solution of $\Delta_g u = 0$ where u has an expansion of this type with any prescribed smooth leading coefficient $a_0(y)$; in any case, the upshot is that the maximal domain is far bigger than the minimal domain in this case

Proof of Proposition 1

- the width of this weight interval is $2 - \alpha$, whereas $\gamma_+ - \gamma_- = \alpha(n/2 - 1) + 1$. We claim that

$$\gamma_- < \mu_- < \mu_+ < \gamma_+$$

precisely when $\alpha > 2/n$, which is verified by noting that $\alpha(n/2 - 1) + 1 > 2 - \alpha$ precisely then

- however, when $\alpha \leq 2/n$, then we can only deduce that

$$u(x, y) \sim \sum a_j(y) x^{\gamma_- + j} + \sum b_j(y) x^{\gamma_+ + j} \quad (4)$$

- this asymptotic expansion has some complicating features, such as that if $a_0 \neq 0$, then the coefficients a_j, b_j may only have finite regularity (and will have negative Sobolev regularity for large j)
- conversely, there exists a solution of $\Delta_g u = 0$ where u has an expansion of this type with any prescribed smooth leading coefficient $a_0(y)$; in any case, the upshot is that the maximal domain is far bigger than the minimal domain in this case

Proof of Proposition 1

- the width of this weight interval is $2 - \alpha$, whereas $\gamma_+ - \gamma_- = \alpha(n/2 - 1) + 1$. We claim that

$$\gamma_- < \mu_- < \mu_+ < \gamma_+$$

precisely when $\alpha > 2/n$, which is verified by noting that $\alpha(n/2 - 1) + 1 > 2 - \alpha$ precisely then

- however, when $\alpha \leq 2/n$, then we can only deduce that

$$u(x, y) \sim \sum a_j(y) x^{\gamma_- + j} + \sum b_j(y) x^{\gamma_+ + j} \quad (4)$$

- this asymptotic expansion has some complicating features, such as that if $a_0 \neq 0$, then the coefficients a_j, b_j may only have finite regularity (and will have negative Sobolev regularity for large j)
- conversely, there exists a solution of $\Delta_g u = 0$ where u has an expansion of this type with any prescribed smooth leading coefficient $a_0(y)$; in any case, the upshot is that the maximal domain is far bigger than the minimal domain in this case

Proof of Proposition 1

- the width of this weight interval is $2 - \alpha$, whereas $\gamma_+ - \gamma_- = \alpha(n/2 - 1) + 1$. We claim that

$$\gamma_- < \mu_- < \mu_+ < \gamma_+$$

precisely when $\alpha > 2/n$, which is verified by noting that $\alpha(n/2 - 1) + 1 > 2 - \alpha$ precisely then

- however, when $\alpha \leq 2/n$, then we can only deduce that

$$u(x, y) \sim \sum a_j(y) x^{\gamma_- + j} + \sum b_j(y) x^{\gamma_+ + j} \quad (4)$$

- this asymptotic expansion has some complicating features, such as that if $a_0 \neq 0$, then the coefficients a_j, b_j may only have finite regularity (and will have negative Sobolev regularity for large j)
- conversely, there exists a solution of $\Delta_g u = 0$ where u has an expansion of this type with any prescribed smooth leading coefficient $a_0(y)$; in any case, the upshot is that the maximal domain is far bigger than the minimal domain in this case

The spectrum is discrete

Proposition 2 (Discrete spectrum)

Let \mathcal{D} be a domain of self-adjointness for Δ_g . Then (Δ_g, \mathcal{D}) is a Fredholm operator on L^2 with discrete spectrum.

When $\alpha < 2/n$, there are many possible self-adjoint extensions. The one we use, is the Dirichlet extension, corresponds to the choice of domain \mathcal{D}_{Dir} consisting of those $u \in L^2$ such that $\Delta_g u \in L^2$ and where the leading coefficient $a_0(y)$ in expansion (4) vanishes.

Other self-adjoint extensions correspond to other types of conditions on the pair of leading coefficient $(a_0(y), b_0(y))$ in (4). Some of the other standard ones are the Neumann extension, where $b_0(y) \equiv 0$, and the family of Robin extensions, corresponding to conditions of the form $A(y)a_0(y) + B(y)b_0(y) \equiv 0$, where A, B are given smooth functions.

The spectrum is discrete

Proposition 2 (Discrete spectrum)

Let \mathcal{D} be a domain of self-adjointness for Δ_g . Then (Δ_g, \mathcal{D}) is a Fredholm operator on L^2 with discrete spectrum.

When $\alpha < 2/n$, there are many possible self-adjoint extensions. The one we use, is the Dirichlet extension, corresponds to the choice of domain \mathcal{D}_{Dir} consisting of those $u \in L^2$ such that $\Delta_g u \in L^2$ and where the leading coefficient $a_0(y)$ in expansion (4) vanishes.

Other self-adjoint extensions correspond to other types of conditions on the pair of leading coefficient $(a_0(y), b_0(y))$ in (4). Some of the other standard ones are the Neumann extension, where $b_0(y) \equiv 0$, and the family of Robin extensions, corresponding to conditions of the form $A(y)a_0(y) + B(y)b_0(y) \equiv 0$, where A, B are given smooth functions.

The spectrum is discrete

Proposition 2 (Discrete spectrum)

Let \mathcal{D} be a domain of self-adjointness for Δ_g . Then (Δ_g, \mathcal{D}) is a Fredholm operator on L^2 with discrete spectrum.

When $\alpha < 2/n$, there are many possible self-adjoint extensions. The one we use, is the Dirichlet extension, corresponds to the choice of domain \mathcal{D}_{Dir} consisting of those $u \in L^2$ such that $\Delta_g u \in L^2$ and where the leading coefficient $a_0(y)$ in expansion (4) vanishes.

Other self-adjoint extensions correspond to other types of conditions on the pair of leading coefficient $(a_0(y), b_0(y))$ in (4). Some of the other standard ones are the Neumann extension, where $b_0(y) \equiv 0$, and the family of Robin extensions, corresponding to conditions of the form $A(y)a_0(y) + B(y)b_0(y) \equiv 0$, where A, B are given smooth functions.

Proof of proposition 2

- The first step is to show that this operator is Fredholm. This follows from the existence of its parametrix.
- The parametrix G of Δ_g is a 0-pseudodifferential operator of order -2 which maps L^2 onto \mathcal{D} (possibly modulo compact errors), and which satisfies

$$G \circ \Delta_g = \text{Id} - R_1, \quad \text{and} \quad \Delta_g \circ G = \text{Id} - R_2,$$

where R_1 and R_2 are compact operators on L^2 and on \mathcal{D} (with its graph topology) respectively.

- As noted earlier, the construction of this parametrix is one of the standard consequences of 0-ellipticity; details are given in [Maz91]. When $\alpha < 2/n$, a slightly more intricate construction is needed which incorporates the choice of boundary conditions; this appears in [MV14].

Proof of proposition 2

- The first step is to show that this operator is Fredholm. This follows from the existence of its parametrix.
- The parametrix G of Δ_g is a 0-pseudodifferential operator of order -2 which maps L^2 onto \mathcal{D} (possibly modulo compact errors), and which satisfies

$$G \circ \Delta_g = \text{Id} - R_1, \quad \text{and} \quad \Delta_g \circ G = \text{Id} - R_2,$$

where R_1 and R_2 are compact operators on L^2 and on \mathcal{D} (with its graph topology) respectively.

- As noted earlier, the construction of this parametrix is one of the standard consequences of 0-ellipticity; details are given in [Maz91]. When $\alpha < 2/n$, a slightly more intricate construction is needed which incorporates the choice of boundary conditions; this appears in [MV14].

Proof of proposition 2

- The first step is to show that this operator is Fredholm. This follows from the existence of its parametrix.
- The parametrix G of Δ_g is a 0-pseudodifferential operator of order -2 which maps L^2 onto \mathcal{D} (possibly modulo compact errors), and which satisfies

$$G \circ \Delta_g = \text{Id} - R_1, \quad \text{and} \quad \Delta_g \circ G = \text{Id} - R_2,$$

where R_1 and R_2 are compact operators on L^2 and on \mathcal{D} (with its graph topology) respectively.

- As noted earlier, the construction of this parametrix is one of the standard consequences of 0-ellipticity; details are given in [Maz91]. When $\alpha < 2/n$, a slightly more intricate construction is needed which incorporates the choice of boundary conditions; this appears in [MV14].

Proof of proposition 2

- The key point here is that the operator G is constructed as an element of the 0-pseudodifferential calculus:
 - The Schwartz kernel is well-understood, as a distribution on $\Omega \times \Omega$.
 - It has asymptotic expansions at the boundary faces of the product, and equally explicit expansion near the corner of Ω^2 (which is $\partial\Omega \times \partial\Omega$).
- The upshot, however, is that it then follows by general properties of such pseudodifferential operators proved in [Maz91] that G is bounded on L^2 . Of course, as a pseudoinverse to Δ_g , its range must lie in \mathcal{D} .
- Since G is a 0-pseudodifferential operator of order -2 , it is clear that the elements in $G(L^2)$ have two derivatives in L^2 , at least in the interior of Ω .
- Slightly more is true: for any $f \in L^2$ and any two vector fields $V_1, V_2 \in \mathcal{V}_0(\Omega)$, we must have that $V_1 V_2 (Gf) \in x^\varepsilon L^2$ for some fixed $\varepsilon > 0$ which is independent of f .

Proof of proposition 2

- The key point here is that the operator G is constructed as an element of the 0-pseudodifferential calculus:
 - The Schwartz kernel is well-understood, as a distribution on $\Omega \times \Omega$.
 - It has asymptotic expansions at the boundary faces of the product, and equally explicit expansion near the corner of Ω^2 (which is $\partial\Omega \times \partial\Omega$).
- The upshot, however, is that it then follows by general properties of such pseudodifferential operators proved in [Maz91] that G is bounded on L^2 . Of course, as a pseudoinverse to Δ_g , its range must lie in \mathcal{D} .
- Since G is a 0-pseudodifferential operator of order -2 , it is clear that the elements in $G(L^2)$ have two derivatives in L^2 , at least in the interior of Ω .
- Slightly more is true: for any $f \in L^2$ and any two vector fields $V_1, V_2 \in \mathcal{V}_0(\Omega)$, we must have that $V_1 V_2 (Gf) \in x^\varepsilon L^2$ for some fixed $\varepsilon > 0$ which is independent of f .

Proof of proposition 2

- The key point here is that the operator G is constructed as an element of the 0-pseudodifferential calculus:
 - The Schwartz kernel is well-understood, as a distribution on $\Omega \times \Omega$.
 - It has asymptotic expansions at the boundary faces of the product, and equally explicit expansion near the corner of Ω^2 (which is $\partial\Omega \times \partial\Omega$).
- The upshot, however, is that it then follows by general properties of such pseudodifferential operators proved in [Maz91] that G is bounded on L^2 . Of course, as a pseudoinverse to Δ_g , its range must lie in \mathcal{D} .
- Since G is a 0-pseudodifferential operator of order -2 , it is clear that the elements in $G(L^2)$ have two derivatives in L^2 , at least in the interior of Ω .
- Slightly more is true: for any $f \in L^2$ and any two vector fields $V_1, V_2 \in \mathcal{V}_0(\Omega)$, we must have that $V_1 V_2 (Gf) \in x^\varepsilon L^2$ for some fixed $\varepsilon > 0$ which is independent of f .

Proof of proposition 2

- The key point here is that the operator G is constructed as an element of the 0-pseudodifferential calculus:
 - The Schwartz kernel is well-understood, as a distribution on $\Omega \times \Omega$.
 - It has asymptotic expansions at the boundary faces of the product, and equally explicit expansion near the corner of Ω^2 (which is $\partial\Omega \times \partial\Omega$).
- The upshot, however, is that it then follows by general properties of such pseudodifferential operators proved in [Maz91] that G is bounded on L^2 . Of course, as a pseudoinverse to Δ_g , its range must lie in \mathcal{D} .
- Since G is a 0-pseudodifferential operator of order -2 , it is clear that the elements in $G(L^2)$ have two derivatives in L^2 , at least in the interior of Ω .
- Slightly more is true: for any $f \in L^2$ and any two vector fields $V_1, V_2 \in \mathcal{V}_0(\Omega)$, we must have that $V_1 V_2(Gf) \in x^\varepsilon L^2$ for some fixed $\varepsilon > 0$ which is independent of f .

Proof of proposition 2

- The key point here is that the operator G is constructed as an element of the 0-pseudodifferential calculus:
 - The Schwartz kernel is well-understood, as a distribution on $\Omega \times \Omega$.
 - It has asymptotic expansions at the boundary faces of the product, and equally explicit expansion near the corner of Ω^2 (which is $\partial\Omega \times \partial\Omega$).
- The upshot, however, is that it then follows by general properties of such pseudodifferential operators proved in [Maz91] that G is bounded on L^2 . Of course, as a pseudoinverse to Δ_g , its range must lie in \mathcal{D} .
- Since G is a 0-pseudodifferential operator of order -2 , it is clear that the elements in $G(L^2)$ have two derivatives in L^2 , at least in the interior of Ω .
- Slightly more is true: for any $f \in L^2$ and any two vector fields $V_1, V_2 \in \mathcal{V}_0(\Omega)$, we must have that $V_1 V_2(Gf) \in x^\varepsilon L^2$ for some fixed $\varepsilon > 0$ which is independent of f .

Proof of proposition 2

- This is summarized by saying that $G: L^2 \rightarrow x^\varepsilon H_0^2$, where the range is a weighted 0-Sobolev space.
- We may then invoke the L^2 version of the Arzelà–Ascoli theorem, which may be used to prove that $x^\varepsilon H_0^2 \hookrightarrow L^2$ is a compact embedding.
- This shows that the domain of Δ_g is compactly contained within L^2 , and hence that (Δ_g, \mathcal{D}) has discrete spectrum.
- A few more words about this parametrix construction, particularly when $\alpha > 2/n$. Write $\Delta_g = x^{\alpha/2-1} L x^{\alpha/2-1}$; as noted earlier, L is an elliptic 0-operator. The singular factor has been distributed on opposite sides of L to preserve symmetry.
- Let \overline{G} be a parametrix for L as constructed in [Maz91]. Thus

$$\text{Id} - L\overline{G} = R'_1 \quad \text{and} \quad \text{Id} - \overline{G}L = R'_2$$

Proof of proposition 2

- This is summarized by saying that $G: L^2 \rightarrow x^\varepsilon H_0^2$, where the range is a weighted 0-Sobolev space.
- We may then invoke the L^2 version of the Arzelà–Ascoli theorem, which may be used to prove that $x^\varepsilon H_0^2 \hookrightarrow L^2$ is a compact embedding.
- This shows that the domain of Δ_g is compactly contained within L^2 , and hence that (Δ_g, \mathcal{D}) has discrete spectrum.
- A few more words about this parametrix construction, particularly when $\alpha > 2/n$. Write $\Delta_g = x^{\alpha/2-1} L x^{\alpha/2-1}$; as noted earlier, L is an elliptic 0-operator. The singular factor has been distributed on opposite sides of L to preserve symmetry.
- Let \overline{G} be a parametrix for L as constructed in [Maz91]. Thus

$$\text{Id} - L\overline{G} = R'_1 \quad \text{and} \quad \text{Id} - \overline{G}L = R'_2$$

Proof of proposition 2

- This is summarized by saying that $G: L^2 \rightarrow x^\varepsilon H_0^2$, where the range is a weighted 0-Sobolev space.
- We may then invoke the L^2 version of the Arzelà–Ascoli theorem, which may be used to prove that $x^\varepsilon H_0^2 \hookrightarrow L^2$ is a compact embedding.
- This shows that the domain of Δ_g is compactly contained within L^2 , and hence that (Δ_g, \mathcal{D}) has discrete spectrum.
- A few more words about this parametrix construction, particularly when $\alpha > 2/n$. Write $\Delta_g = x^{\alpha/2-1} L x^{\alpha/2-1}$; as noted earlier, L is an elliptic 0-operator. The singular factor has been distributed on opposite sides of L to preserve symmetry.
- Let \overline{G} be a parametrix for L as constructed in [Maz91]. Thus

$$\text{Id} - L\overline{G} = R'_1 \quad \text{and} \quad \text{Id} - \overline{G}L = R'_2$$

Proof of proposition 2

- This is summarized by saying that $G: L^2 \rightarrow x^\varepsilon H_0^2$, where the range is a weighted 0-Sobolev space.
- We may then invoke the L^2 version of the Arzelà–Ascoli theorem, which may be used to prove that $x^\varepsilon H_0^2 \hookrightarrow L^2$ is a compact embedding.
- This shows that the domain of Δ_g is compactly contained within L^2 , and hence that (Δ_g, \mathcal{D}) has discrete spectrum.
- A few more words about this parametrix construction, particularly when $\alpha > 2/n$. Write $\Delta_g = x^{\alpha/2-1} L x^{\alpha/2-1}$; as noted earlier, L is an elliptic 0-operator. The singular factor has been distributed on opposite sides of L to preserve symmetry.
- Let \overline{G} be a parametrix for L as constructed in [Maz91]. Thus

$$\text{Id} - L\overline{G} = R'_1 \quad \text{and} \quad \text{Id} - \overline{G}L = R'_2$$

Proof of proposition 2

- The error terms R'_1, R'_2 are operators with smooth kernels on the interior of $\Omega \times \Omega$, and which admit classical expansions at all boundary faces of a certain resolution (or blow-up) of this product, with coefficients in these expansion smooth functions on the corresponding boundary faces.
- We then write $G = x^{1-\alpha/2} \overline{G} x^{1-\alpha/2}$, so that $\Delta_g \circ G = \text{Id} - x^{\alpha/2-1} R_1 x^{\alpha/2-1} = I - R_1$, $G \circ \Delta_g = \text{Id} - x^{\alpha/2-1} R'_2 x^{\alpha/2-1} = \text{Id} - R_2$.
- These remainder terms are much better, inasmuch as they have smooth Schwartz kernels which have polyhomogeneous expansions at the two boundary hypersurfaces of Ω^2 , without need for the resolution (or blow-up) process.
- If $\Delta_g u = f \in L^2$, then applying G , we get that $u = R_1 u + Gf = R_1 u + x^{1-\alpha/2} \overline{G} x^{1-\alpha/2} f$.
- The first term is polyhomogeneous on Ω , and decays at a fixed rate strictly greater than the L^2 cutoff. When $\alpha > 2/n$, the range of G lies in $x^{2-\alpha} H_0^2$.
- This range is identified with the domain of self-adjointness \mathcal{D} (again, when $\alpha > 2/n$), hence, as described above, $\mathcal{D} \subset L^2$ is indeed compact.

Proof of proposition 2

- The error terms R'_1, R'_2 are operators with smooth kernels on the interior of $\Omega \times \Omega$, and which admit classical expansions at all boundary faces of a certain resolution (or blow-up) of this product, with coefficients in these expansion smooth functions on the corresponding boundary faces.
- We then write $G = x^{1-\alpha/2}\overline{G}x^{1-\alpha/2}$, so that $\Delta_g \circ G = \text{Id} - x^{\alpha/2-1}R_1x^{\alpha/2-1} = I - R_1$, $G \circ \Delta_g = \text{Id} - x^{\alpha/2-1}R'_2x^{\alpha/2-1} = \text{Id} - R_2$.
- These remainder terms are much better, inasmuch as they have smooth Schwartz kernels which have polyhomogeneous expansions at the two boundary hypersurfaces of Ω^2 , without need for the resolution (or blow-up) process.
- If $\Delta_g u = f \in L^2$, then applying G , we get that $u = R_1 u + Gf = R_1 u + x^{1-\alpha/2}\overline{G}x^{1-\alpha/2}f$.
- The first term is polyhomogeneous on Ω , and decays at a fixed rate strictly greater than the L^2 cutoff. When $\alpha > 2/n$, the range of G lies in $x^{2-\alpha}H_0^2$.
- This range is identified with the domain of self-adjointness \mathcal{D} (again, when $\alpha > 2/n$), hence, as described above, $\mathcal{D} \subset L^2$ is indeed compact.

Proof of proposition 2

- The error terms R'_1, R'_2 are operators with smooth kernels on the interior of $\Omega \times \Omega$, and which admit classical expansions at all boundary faces of a certain resolution (or blow-up) of this product, with coefficients in these expansion smooth functions on the corresponding boundary faces.
- We then write $G = x^{1-\alpha/2}\overline{G}x^{1-\alpha/2}$, so that $\Delta_g \circ G = \text{Id} - x^{\alpha/2-1}R_1x^{\alpha/2-1} = I - R_1$, $G \circ \Delta_g = \text{Id} - x^{\alpha/2-1}R'_2x^{\alpha/2-1} = \text{Id} - R_2$.
- These remainder terms are much better, inasmuch as they have smooth Schwartz kernels which have polyhomogeneous expansions at the two boundary hypersurfaces of Ω^2 , without need for the resolution (or blow-up) process.
- If $\Delta_g u = f \in L^2$, then applying G , we get that $u = R_1 u + Gf = R_1 u + x^{1-\alpha/2}\overline{G}x^{1-\alpha/2}f$.
- The first term is polyhomogeneous on Ω , and decays at a fixed rate strictly greater than the L^2 cutoff. When $\alpha > 2/n$, the range of G lies in $x^{2-\alpha}H_0^2$.
- This range is identified with the domain of self-adjointness \mathcal{D} (again, when $\alpha > 2/n$), hence, as described above, $\mathcal{D} \subset L^2$ is indeed compact.

Proof of proposition 2

- The error terms R'_1, R'_2 are operators with smooth kernels on the interior of $\Omega \times \Omega$, and which admit classical expansions at all boundary faces of a certain resolution (or blow-up) of this product, with coefficients in these expansion smooth functions on the corresponding boundary faces.
- We then write $G = x^{1-\alpha/2}\overline{G}x^{1-\alpha/2}$, so that $\Delta_g \circ G = \text{Id} - x^{\alpha/2-1}R_1x^{\alpha/2-1} = I - R_1$, $G \circ \Delta_g = \text{Id} - x^{\alpha/2-1}R'_2x^{\alpha/2-1} = \text{Id} - R_2$.
- These remainder terms are much better, inasmuch as they have smooth Schwartz kernels which have polyhomogeneous expansions at the two boundary hypersurfaces of Ω^2 , without need for the resolution (or blow-up) process.
- If $\Delta_g u = f \in L^2$, then applying G , we get that $u = R_1 u + Gf = R_1 u + x^{1-\alpha/2}\overline{G}x^{1-\alpha/2}f$.
- The first term is polyhomogeneous on Ω , and decays at a fixed rate strictly greater than the L^2 cutoff. When $\alpha > 2/n$, the range of G lies in $x^{2-\alpha}H_0^2$.
- This range is identified with the domain of self-adjointness \mathcal{D} (again, when $\alpha > 2/n$), hence, as described above, $\mathcal{D} \subset L^2$ is indeed compact.

Proof of proposition 2

- The error terms R'_1, R'_2 are operators with smooth kernels on the interior of $\Omega \times \Omega$, and which admit classical expansions at all boundary faces of a certain resolution (or blow-up) of this product, with coefficients in these expansion smooth functions on the corresponding boundary faces.
- We then write $G = x^{1-\alpha/2}\overline{G}x^{1-\alpha/2}$, so that $\Delta_g \circ G = \text{Id} - x^{\alpha/2-1}R_1x^{\alpha/2-1} = I - R_1$, $G \circ \Delta_g = \text{Id} - x^{\alpha/2-1}R'_2x^{\alpha/2-1} = \text{Id} - R_2$.
- These remainder terms are much better, inasmuch as they have smooth Schwartz kernels which have polyhomogeneous expansions at the two boundary hypersurfaces of Ω^2 , without need for the resolution (or blow-up) process.
- If $\Delta_g u = f \in L^2$, then applying G , we get that $u = R_1 u + Gf = R_1 u + x^{1-\alpha/2}\overline{G}x^{1-\alpha/2}f$.
- The first term is polyhomogeneous on Ω , and decays at a fixed rate strictly greater than the L^2 cutoff. When $\alpha > 2/n$, the range of G lies in $x^{2-\alpha}H_0^2$.
- This range is identified with the domain of self-adjointness \mathcal{D} (again, when $\alpha > 2/n$), hence, as described above, $\mathcal{D} \subset L^2$ is indeed compact.

Proof of proposition 2

- The error terms R'_1, R'_2 are operators with smooth kernels on the interior of $\Omega \times \Omega$, and which admit classical expansions at all boundary faces of a certain resolution (or blow-up) of this product, with coefficients in these expansion smooth functions on the corresponding boundary faces.
- We then write $G = x^{1-\alpha/2}\overline{G}x^{1-\alpha/2}$, so that $\Delta_g \circ G = \text{Id} - x^{\alpha/2-1}R_1x^{\alpha/2-1} = I - R_1$, $G \circ \Delta_g = \text{Id} - x^{\alpha/2-1}R'_2x^{\alpha/2-1} = \text{Id} - R_2$.
- These remainder terms are much better, inasmuch as they have smooth Schwartz kernels which have polyhomogeneous expansions at the two boundary hypersurfaces of Ω^2 , without need for the resolution (or blow-up) process.
- If $\Delta_g u = f \in L^2$, then applying G , we get that $u = R_1 u + Gf = R_1 u + x^{1-\alpha/2}\overline{G}x^{1-\alpha/2}f$.
- The first term is polyhomogeneous on Ω , and decays at a fixed rate strictly greater than the L^2 cutoff. When $\alpha > 2/n$, the range of G lies in $x^{2-\alpha}H_0^2$.
- This range is identified with the domain of self-adjointness \mathcal{D} (again, when $\alpha > 2/n$), hence, as described above, $\mathcal{D} \subset L^2$ is indeed compact.

- [Maz91] Rafe Mazzeo. Elliptic theory of differential edge operators. I. *Comm. Partial Differential Equations*, 16(10):1615–1664, 1991.
- [MV14] Rafe Mazzeo and Boris Vertman. Elliptic theory of differential edge operators, II: Boundary value problems. *Indiana Univ. Math. J.*, 63(6):1911–1955, 2014.